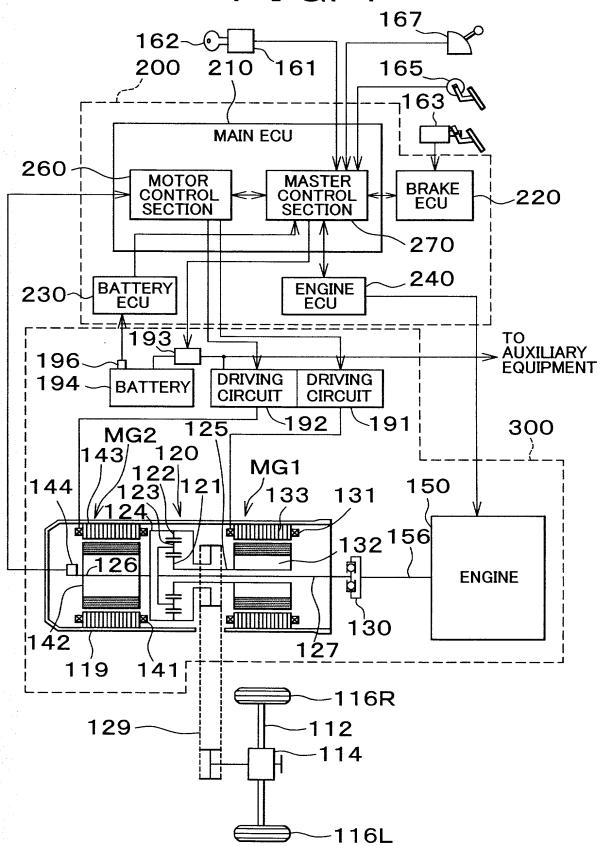
100

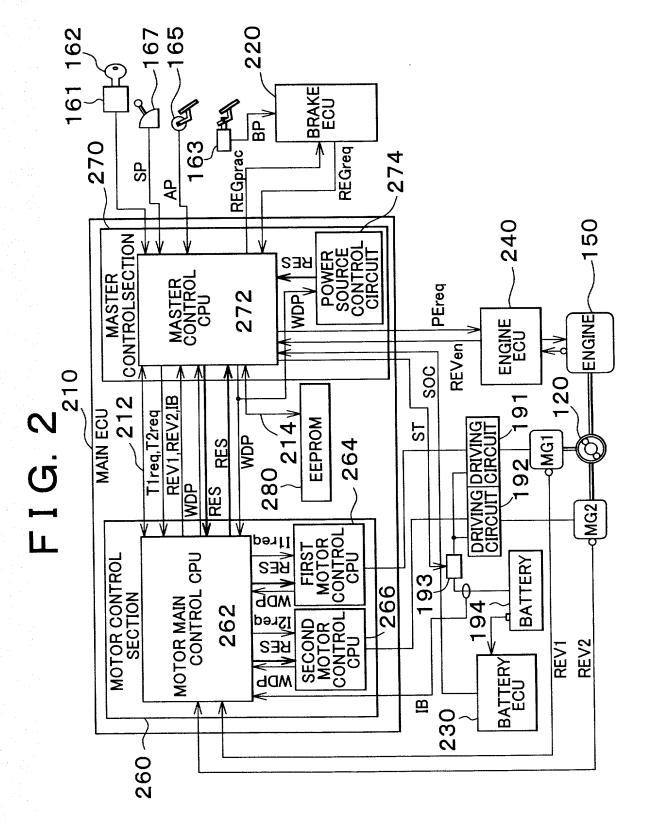
den's agent

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#### F I G. 1

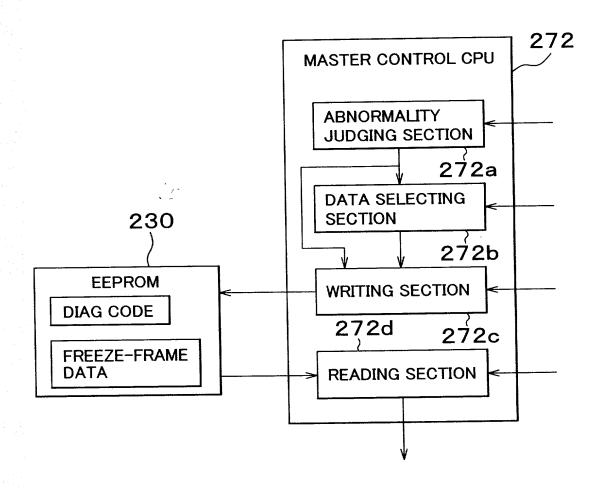


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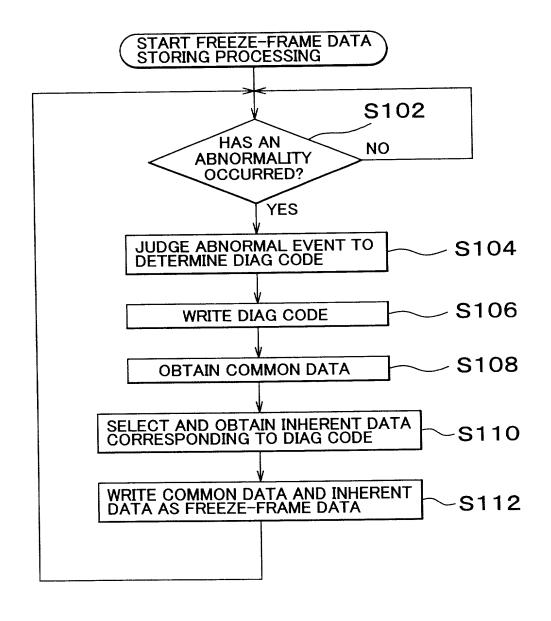
FIG. 3



Buth wed

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FIG. 4



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FIG. 5A



FIG. 5B



FIG. 5C



FIG. 5D

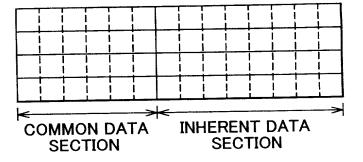
P1300	1
P1100	
P1200	

FIG. 5E



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#### FIG. 6A



#### FIG. 6B

#### FRAME1

αt1	β t1	γt1	at1	bt1	ct1	dt1
T					 	
	<del>                                     </del>		i i	1 1		i i

## FIG. 6C

# FRAME1 FRAME2

αt1	β t1	γt1	at1	bt1	ct1	dt1
αt2	β t2	γt2	et2	ft2	gt2	ht2
		1 1			1	
				<del>                                     </del>		

#### FIG. 6D

FRAME1

FRAME2

FRAME3

αt1	β t1	γt1	at1	bt1	ct1	dt1
αt2	β t2	γt2	et2	ft2	gt2	ht2
	β t3				kt3	
				1 1		

## FIG. 6E

FRAME1

FRAME2

FRAME3

FRAME4

αt1	β t1	γt1	at1	bt1	ct1	dt1
αt2	β t2	γt2	et2	ft2	gt2	ht2
αt3	β t3	γt3	it3	jt3	kt3	lt3
αt4	β t4	γt4	mt4	nt4	ot4	pt4

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# FIG. 7A-1

PID=0,FRAME NUMBER=1  $\alpha$ t1  $\beta$ t1  $\gamma$ t1 at1

F I G. 7A-2

PID=1,FRAME NUMBER=1 bt1 ct1 dt1

FIG. 7A-3

PID=0,FRAME NUMBER=2 αt2 βt2 γt2 et2

F I G. 7B-1

PID=1,FRAME NUMBER=2 ft2 gt2 ht2

FIG. 7B-2

PID=0,FRAME NUMBER=3  $\alpha$  t3  $\beta$  t3  $\gamma$  t3 it3

FIG. 7C-1

PID=1,FRAME NUMBER=3 jt3 kt3 lt3

FIG. 7C-2

PID=0,FRAME NUMBER=4  $\alpha$  t4  $\beta$  t4  $\gamma$  t4 mt4

FIG. 7C-3

PID=1,FRAME NUMBER=4 nt4 ot4 pt4

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# FIG. 8

FRAME1 FRAME2

FRAME3 FRAME4

αt1	β t1	γt1	at1	bt1	ct1	dt1
αt2	β t2	γt2	ft2	ht2		
αt3	β t3	γt3	it3	kt3	lt3	
αt4	β t4	γt4	mt4	nt4		

#### FIG. 9

FRAME1 FRAME2 FRAME3

FRAME3 FRAME4

αt1	βt1	γt1	at1	bt1	ct1	dt1
αt2	β t2	γt2	et2		ft2	ht2
αt3	β t3	γt3	it3	kt3		lt3
αt4	β t4	γt4	mt4		nt4	pt4

#### FIG. 10

FRAME1 FRAME2

FRAME3

FRAME4

αt1	β t1	γt1	at1	bt1	ct1	dt1
αt2	β t2	γt2	ft2	ht	t2	
αt3	β t3	γt3	it3	kt3		lt3
αt4	β t4	γt4	mt4	nt4		

# FIG. 11

FRAME1

FRAME2 FRAME3

FRAME4

αt1	β t1	γt1	at1	bt1	ct1	dt1
αt2	β t2	γt2	ft2			ht2
αt3	β t3	γt3	it3	kt3		lt3
αt4	β t4	γt4		mt4		nt4

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